## Homework assignment no. 1

1. Prove that the problem of computing the convex hull of a set of $n$ points in the plane has an $\Omega(n \log n)$ lower bound. Hint: Show that a set of $n$ real numbers can be sorted in time $O(n)$, plus the time needed for a single convex hull computation.
2. A slab is a region of the plane that is defined by two parallel lines. Its width is the distance between the lines defining it. Let $P$ be a set of $n$ points in the plane. The width of $P$ is the width of a minimum-width slab that contains $P$. Describe an $O(n \log n)$-time algorithm for computing the width of $P$. (Hint: Show that the width of $P$ is determined by a pair of parallel lines supporting the convex hull of $P$, where at least one of them contains an edge of the convex hull.)
3. Let $P$ be a set of $n$ points in the plane. A point $p \in P$ is $h$-maximal, for $0 \leq h \leq n-1$, if the number of points in $P$ which are both above and to the right of $p$ is at most $h$. $p$ is maximal if it is 0 -maximal.
(i) Give a four-point example $P$ that has both a maximal point in the interior of $C H(P)$, and a vertex of $C H(P)$ that is not maximal.
(ii) Describe an $O(n \log n)$-time algorithm to compute the $h$-maximal points of $P$, where $|P|=n$ and $h$ is a non-negative integer.
4. Let $C_{1}$ and $C_{2}$ be two convex polygons, each with $n$ vertices. (Each polygon is given by the sequence of its vertices in clockwise order.)
(i) Show that the number of intersection points between edges of $C_{1}$ and edges of $C_{2}$ is $\Theta(n)$.
(ii) Describe an $O(n)$-time algorithm for computing all these intersection points.
5. Let $S_{1}$ be a set of $n$ disjoint horizontal segments, and let $S_{2}$ be a set of $n$ disjoint vertical segments. Describe an $O(n \log n)$-time algorithm for counting the number of intersections in $S_{1} \cup S_{2}$.

Submission: November 14, 2018.

