

# Final #1

Mark the correct answer in each part of the following questions.

1. We are working with a system implementing the IEEE standard with single precision and rounding to the nearest. Denote by  $\oplus$  the binary operation of addition, as performed on floating point numbers in our system.
  - (a) The largest positive integer  $n$  for which  $2^n \oplus n$  is a floating point number and  $2^n \oplus n > 2^n$  is
    - (i) 23.
    - (ii) 24.
    - (iii) 27.
    - (iv) 28.
    - (v) None of the above.
  - (b) Consider the approximation formula

$$f'(x) \approx \frac{f(x+h) - f(x)}{h}$$

( $h$  a non-zero number close to 0) for estimating  $f'(x)$ . Suppose we use the formula to estimate  $f'(1)$  for the function  $f(x) = \sqrt{x}$ . For  $k = 1, 2, \dots$ , denote by  $e_k$  the absolute value of the error when we take  $h = k\varepsilon$ . Assume that, when the system is asked to compute  $\sqrt{a}$  for some floating point number  $a$ , it returns the floating point closest to  $\sqrt{a}$ .

- (i)  $e_1 < e_2 < e_3$ .
- (ii)  $e_1 > e_2 > e_3$ .
- (iii)  $e_1 > e_3 > e_2$ .

- (iv)  $e_3 > e_1 > e_2$ .
- (v) None of the above.

2. (a) Consider the equation:

$$\frac{\pi}{3} \sin x = x.$$

Notice that  $\xi = \pi/6$  is a solution and that, for each  $\alpha \neq 0$ , the equation is equivalent to:

$$\frac{\pi}{3\alpha} \sin x + \frac{\alpha - 1}{\alpha} x = x.$$

Thus, defining

$$g_\alpha(x) = \frac{\pi}{3\alpha} \sin x + \frac{\alpha - 1}{\alpha} x,$$

the original equation may be tackled using a fixed point iteration for any  $g$ . Suppose we start from a point sufficiently close to  $\xi$ .

- (i) If  $\alpha > 1 - \frac{\pi}{2\sqrt{3}}$ , then the convergence is linear, but becomes slower as  $\alpha$  increases. For  $\alpha = 1 - \frac{\pi}{2\sqrt{3}}$  the convergence is quadratic. For  $\frac{1}{2} - \frac{\pi}{4\sqrt{3}} < \alpha < 1 - \frac{\pi}{2\sqrt{3}}$  the convergence is linear. For  $\alpha < \frac{1}{2} - \frac{\pi}{4\sqrt{3}}$  the point  $\xi$  is not attracting.
  - (ii) The convergence is at least linear for every  $\alpha \neq 0$  and quadratic for at least one  $\alpha$ .
  - (iii) The convergence is quadratic (or faster) for no  $\alpha \neq 0$ .
  - (iv) If  $\alpha > \frac{1}{2} - \frac{\pi}{4\sqrt{3}}$ , then the convergence is linear. If  $\alpha = \frac{1}{2} - \frac{\pi}{4\sqrt{3}}$ , then the convergence is at least quadratic.
  - (v) None of the above.
- (b) Newton's method is employed to solve the equation  $\cos(\pi e^x) + 1 = 0$ . If we start sufficiently close to the root  $\xi = 0$  of the equation then:
- (i) The convergence is linear, but slightly slower than that of the bisection method.
  - (ii) The convergence is linear, with speed almost the same as that of the bisection method.

- (iii) The convergence is linear, but slightly faster than that of the bisection method.
- (iv) The convergence is quadratic.
- (v) None of the above.
3. (a) We approximate  $\int_0^{\pi/12} \operatorname{tg} 4x dx$  by dividing the interval  $[0, \pi/12]$  into  $n$  sub-intervals, not necessarily of equal length, and using one of the rules for each of these intervals. Let  $E_1$  be the total error if the rule used is the rectangle rule,  $E_2$  – if it is the midpoint rule, and  $E_3$  – if it is Simpson's rule. The signs of the errors are as follows.
- (i)  $E_1 > 0, E_2 > 0, E_3 > 0$ .
- (ii)  $E_1 < 0, E_2 > 0, E_3 > 0$ .
- (iii)  $E_1 > 0, E_2 > 0, E_3 < 0$ .
- (iv) The sign of at least one of the  $E_i$ 's depends in a non-trivial way on  $n$  and the division points.
- (v) None of the above.
- (b) We estimate  $\int_0^1 \ln(x(x+1)) dx$  by dividing the interval  $[0, 1]$  into  $n$  sub-intervals of equal length, and using the rectangle rule for each of them, but with the right endpoint of each sub-interval instead of its left endpoint. Let  $E$  be the error. For sufficiently large  $n$
- (i)  $|E|$  becomes arbitrarily large.
- (ii)  $|E| \approx \frac{C}{n}$  for some constant  $C > 0$ .
- (iii)  $|E| \approx \frac{\ln 4\pi n}{2n}$ .
- (iv)  $|E| \approx \frac{C}{\ln n}$  for some constant  $C > 0$ .
- (v) None of the above.
- (c) We estimate  $\int_0^{\pi/3} \sqrt{\cos x} dx$  by dividing the interval  $[0, \pi/3]$  into  $n$  sub-intervals of equal length, and using the midpoint rule for each of them. Let  $E$  be the error. Then:
- (i)  $E \approx -\frac{\pi^2 \sqrt{6}}{864n^2}$ .
- (ii)  $E \approx -\frac{\pi^2 \sqrt{2}}{864n^2}$ .
- (iii)  $E \approx \frac{\pi^2 \sqrt{2}}{864n^2}$ .

- (iv)  $E \approx \frac{\pi^2\sqrt{6}}{864n^2}$ .
- (v) None of the above.

4. We are interested in finding an approximation formula of the form

$$\int_0^1 f(x)dx \approx w_1f(1/3) + w_2f(x_2),$$

with some appropriate weights  $w_1, w_2$  and point  $x_2 \in [0, 1]$ , that will be completely accurate in case  $f$  is a polynomial of degree not exceeding 2.

- (a) We must choose:
  - (i)  $w_1 = w_2 = 1/2, x_2 = 2/3$ .
  - (ii)  $w_1 = 1/3, w_2 = 2/3, x_2 = 1/2$ .
  - (iii)  $w_1 = w_2 = 1/2, x_2 = 1/2$ .
  - (iv)  $w_1 = 3/4, w_2 = 1/4, x_2 = 1$ .
  - (v) None of the above.
- (b) Suppose there exist  $w_1, w_2, x_2$  for which the above requirements are satisfied. Let  $\langle \cdot, \cdot \rangle$  be the inner product defined on the space of all real polynomials by

$$\langle Q_1, Q_2 \rangle = \int_0^1 Q_1(x)Q_2(x)dx, \quad Q_1, Q_2 \in \mathbf{R}[x].$$

Consider the polynomials

$$P_1(x) = x - x_2, \quad P_2(x) = (x - 1/3)(x - x_2).$$

- (i) Neither one of the polynomials  $P_i$  is orthogonal to all constant polynomials.
- (ii) The polynomial  $P_1$  is not orthogonal to all constant polynomials. The polynomial  $P_2$  is orthogonal to all constant polynomials, but not to all polynomials of degree not exceeding 1.
- (iii) The polynomial  $P_1$  is orthogonal to all polynomials of degree not exceeding 1, but not to all polynomials of degree not exceeding 2. The polynomial  $P_2$  is orthogonal to all constant polynomials, but not to all polynomials of degree not exceeding 1.

- (iv) The polynomial  $P_1$  is orthogonal to all polynomials of degree not exceeding 2, but not to all polynomials of degree not exceeding 3. The polynomial  $P_2$  is orthogonal to all polynomials of degree not exceeding 1, but not to all polynomials of degree not exceeding 2.
- (v) None of the above.

## Solutions

1. (a) Integers in the range  $[16, 31]$  are of the form  $1.\underbrace{b_1b_2b_3b_40\dots0}_{23}\cdot 2^4$ .

For any  $n \in [16, 31]$ , the addition of  $n$  to  $2^n$  requires shifting the representation of  $n$  by  $n - 4$  bits to the right, to obtain both numbers represented with the same exponent. As long as  $n - 4 \leq 23$ , we clearly have  $2^n \oplus n > 2^n$ , because the most significant digit (the implicit 1 to the left of the binary point) of  $n$  is still shifted to one of the first 23 digits after the binary point. For  $n = 28$ , which requires 24 shifts, the representation is  $0.\underbrace{0\dots0}_{23}111 \cdot 2^{28}$ . Hence

$$2^{28} + 28 = 1 \cdot 2^{28} + 0.\underbrace{0\dots0}_{23}111 \cdot 2^{28} = 1.\underbrace{0\dots0}_{23}111 \cdot 2^{28},$$

which is rounded to

$$1.\underbrace{0\dots0}_{22}1 \cdot 2^{28} = 2^{28} + 2^5 > 2^{28}.$$

For  $n > 28$ , the shift will be of at least 25 places to the right to obtain the same exponent for  $n$ , leading to  $0.\underbrace{0\dots0}_{23}01b_1\dots \cdot 2^n$

(with the leading 1 where shown or even farther to the right). It follows that  $2^n \oplus n = 2^n$ .

Thus, (iv) is true.

- (b) Clearly,  $f'(1) = \frac{1}{2}$ . Using Taylor's approximation for  $f(x + h)$ , where  $x = 1$ , we obtain  $f(1 + h) = \sqrt{1 + h} \approx 1 + \frac{1}{2}(1 + h - 1)$ . For single precision,  $\varepsilon = 2^{-23}$ , so  $h$  assumes the values  $2^{-23}, 2 \cdot 2^{-23}, 3 \cdot 2^{-23}$ , which will be used for evaluating  $e_1, e_2, e_3$ , respectively. The general expression we are interested in is

$$e_k = |f'(1) - \text{round}((f(1 \oplus k \otimes \varepsilon) \ominus f(1)) \otimes (k \otimes \varepsilon))|, \quad k = 1, 2, 3.$$

(In fact, when we write  $f(a)$  for some floating point number  $a$ , we refer to the approximation provided for  $f(a)$  by the system.)

Hence:

$$e_k \approx \left| \frac{1}{2} - \text{round} \left( \left( \left( 1 \oplus \frac{1}{2} \otimes (1 \oplus k \otimes 2^{-23} \ominus 1) \ominus 1 \right) \otimes (k \otimes 2^{-23}) \right) \right) \right|,$$

for  $k = 1, 2, 3$ . Now we complete the calculation for each  $k$  separately:

- $k = 1$ :

$$\begin{aligned}
& \text{round} \left( \left( \left( 1 \oplus \frac{1}{2} \otimes (1 \oplus 2^{-23} \ominus 1) \ominus 1 \right) \otimes 2^{-23} \right) \right) \\
&= \text{round} \left( \left( \left( 1 \oplus \frac{1}{2} \otimes 2^{-23} \ominus 1 \right) \otimes 2^{-23} \right) \right) \\
&= \text{round} \left( (1 \oplus 2^{-24} \ominus 1) \otimes 2^{-23} \right) \\
&= \text{round} (0 \otimes 2^{-23}) = 0.
\end{aligned}$$

Thus,

$$e_1 = \left| \frac{1}{2} - 0 \right| = \frac{1}{2}.$$

- $k = 2$ :

$$\begin{aligned}
& \text{round} \left( \left( \left( 1 \oplus \frac{1}{2} \otimes (1 \oplus 2 \otimes 2^{-23} \ominus 1) \ominus 1 \right) \otimes (2 \otimes 2^{-23}) \right) \right) \\
&= \text{round} \left( \left( \left( 1 \oplus \frac{1}{2} \otimes 2^{-22} \ominus 1 \right) \otimes 2^{-22} \right) \right) \\
&= \text{round} \left( (1 \oplus 2^{-23} \ominus 1) \otimes 2^{-22} \right) \\
&= \text{round} (2^{-23} \otimes 2^{-22}) = \frac{1}{2}.
\end{aligned}$$

Thus,

$$e_2 = \left| \frac{1}{2} - \frac{1}{2} \right| = 0.$$

•  $k = 3$ :

$$\begin{aligned}
& \text{round} \left( \left( \left( 1 \oplus \frac{1}{2} \otimes (1 \oplus 3 \otimes 2^{-23} \ominus 1) \ominus 1 \right) \otimes (3 \otimes 2^{-23}) \right) \right) \\
&= \text{round} \left( \left( \left( 1 \oplus \frac{1}{2} \otimes 3 \otimes 2^{-23} \ominus 1 \right) \otimes (3 \otimes 2^{-23}) \right) \right) \\
&= \text{round} \left( (1 \oplus 3 \otimes 2^{-24} \ominus 1) \otimes (3 \otimes 2^{-23}) \right) \\
&= \text{round} \left( 2^{-22} \otimes (3 \otimes 2^{-23}) \right) \\
&= \text{round} \left( \frac{2}{3} \right).
\end{aligned}$$

Thus,

$$e_3 = \left| \frac{1}{2} - \text{round} \left( \frac{2}{3} \right) \right| \approx \frac{1}{6}.$$

Thus, (iii) is true.

2. (a) We have

$$g'_\alpha(x) = \frac{\pi}{3\alpha} \cos x + \frac{\alpha - 1}{\alpha}, \quad (\alpha \neq 0),$$

and substituting  $\xi = \pi/6$  we obtain:

$$g'_\alpha(\pi/6) = \frac{\pi}{3\alpha} \cos \frac{\pi}{6} + \frac{\alpha - 1}{\alpha} = 1 - \frac{1}{\alpha} \left( 1 - \frac{\pi}{2\sqrt{3}} \right), \quad (\alpha \neq 0). \quad (1)$$

If  $\alpha = 1 - \frac{\pi}{2\sqrt{3}}$  then  $g'_\alpha(\pi/6) = 0$ , so that the convergence is quadratic. If  $\alpha > 1 - \frac{\pi}{2\sqrt{3}}$  then  $0 < g'_\alpha(\pi/6) < 1$ , so that the convergence is linear. In this case the error decreases (almost) as a geometric series with ratio  $q = g'_\alpha(\pi/6)$ , and since the right-hand side of (1) increases with  $\alpha$  in this range, therefore the convergence becomes slower as  $\alpha$  increases. If  $\frac{1}{2} - \frac{\pi}{4\sqrt{3}} < \alpha < 1 - \frac{\pi}{2\sqrt{3}}$  then  $-1 < g'_\alpha(\pi/6) < 0$ , and the convergence is again linear. If  $\alpha < \frac{1}{2} - \frac{\pi}{4\sqrt{3}}$  then  $g'_\alpha(\pi/6) < -1$ . Since  $|g'_\alpha(\pi/6)| > 1$ , and the fixed point  $\xi$  is not attracting.

Thus, (i) is true.

(b) We have

$$f'(x) = -\pi e^x \sin(\pi e^x)$$

and

$$f''(x) = -\pi e^x \sin(\pi e^x) - (\pi e^x)^2 \cos(\pi e^x),$$

and in particular  $f'(\xi) = 0$  and  $f''(\xi) = \pi^2$ . Thus,  $\xi = 0$  is root of  $f$  of order 2. The iteration function corresponding to Newton's method is:

$$g(x) = x - \frac{f(x)}{f'(x)} = x + \frac{\cos(\pi e^x) + 1}{\pi e^x \sin(\pi e^x)}.$$

Now

$$g'(x) = \frac{(\pi e^x \cos(\pi e^x) + \sin(\pi e^x))e^{-x}}{(\cos(\pi e^x) - 1)\pi}, \quad (2)$$

and a routine calculation yields  $g'(x) = \lim_{x \rightarrow 0} g'(x) = \frac{1}{2}$ . Hence the convergence is linear, with speed almost the same as that of the bisection method.

Thus, (ii) is true.

3. (a) Let  $x_0 = 0 < x_1 < \dots < x_n = \pi/12$  be the division points. The errors  $E_{1,i}$ ,  $E_{2,i}$ , and  $E_{3,i}$  in each sub-interval  $[x_{i-1}, x_i]$ ,  $1 \leq i \leq n$ , when using the rectangle rule, the midpoint rule and Simpson's rule, respectively, are:

$$E_{1,i} = f'(\eta_{1,i}) \frac{(x_i - x_{i-1})^2}{2}, \quad \eta_{1,i} \in (x_{i-1}, x_i),$$

$$E_{2,i} = f''(\eta_{2,i}) \frac{(x_i - x_{i-1})^3}{24}, \quad \eta_{2,i} \in (x_{i-1}, x_i),$$

$$E_{3,i} = -f^{(4)}(\eta_{3,i}) \frac{(x_i - x_{i-1})^5}{90 \cdot 2^5}, \quad \eta_{3,i} \in (x_{i-1}, x_i).$$

The corresponding total errors are:

$$E_1 = \sum_{i=1}^n E_{1,i}, \quad E_2 = \sum_{i=1}^n E_{2,i}, \quad E_3 = \sum_{i=1}^n E_{3,i}.$$

One verifies by induction that  $f^{(k)}(x)$  is a polynomial of degree  $k + 1$  with non-negative coefficients in  $\operatorname{tg} 4x$  for each  $k \geq 0$ . For example,

$$f'(x) = \frac{4}{\cos^2 4x} = 2^2(\operatorname{tg}^2 4x + 1),$$

$$f''(x) = 2^5(\operatorname{tg}^3 4x + \operatorname{tg} 4x),$$

and

$$f^{(4)}(x) = 2^{11}(3\operatorname{tg}^5 4x + 5\operatorname{tg}^3 4x + 2\operatorname{tg} 4x).$$

In particular, since  $\operatorname{tg} 4x$  is positive throughout the interval, so is  $f^{(k)}(x)$  for every  $k$ . Hence,  $E_1 > 0, E_2 > 0, E_3 < 0$ .

Thus, (iii) is true.

(b) Since  $\ln(x(x+1)) = \ln x + \ln(x+1)$ , we have:

$$\int_0^1 \ln(x(x+1))dx = \int_0^1 \ln x dx + \int_0^1 \ln(x+1)dx. \quad (3)$$

Moreover, when approximating the left-hand side of (3) by the rectangle rule (or any other rule for that matter) we obtain the sum of the approximations obtained for the two integrals on the right-hand side. Note that the first integral on the right-hand side of (3) was studied in class. When using the rectangle rule with the right endpoint of each sub-interval instead of its left endpoint, it is approximated as follows:

$$\int_0^1 \ln x dx \approx \frac{1}{n} \sum_{i=1}^n \ln \frac{i}{n} = \frac{1}{n} \ln n! - \ln n. \quad (4)$$

Similarly, for the second integral on the right-hand side of (3) we have:

$$\begin{aligned} \int_0^1 \ln(x+1)dx &\approx \frac{1}{n} \sum_{i=1}^n \ln \left( \frac{i}{n} + 1 \right) \\ &= \frac{1}{n} \ln(2n)! - \frac{1}{n} \ln n! - \ln n. \end{aligned} \quad (5)$$

Substituting (4) and (5) in the right-hand side of (3), we obtain:

$$\int_0^1 \ln(x(x+1))dx \approx \frac{1}{n} \ln(2n)! - 2 \ln n. \quad (6)$$

Now, by Stirling's formula  $(2n)! \approx \sqrt{4\pi n} \left(\frac{2n}{e}\right)^{2n}$ , and therefore:

$$\int_0^1 \ln(x(x+1))dx \approx \frac{1}{2n} \ln 4\pi n + 2 \ln 2 - 2. \quad (7)$$

Since  $\int \ln x dx = x \ln x - x + c$ , we have

$$\begin{aligned} \int_0^1 \ln(x(x+1))dx &= [x \ln x - x + (x+1) \ln(x+1) - (x+1)]_0^1 \\ &= 2 \ln 2 - 2. \end{aligned} \quad (8)$$

By (7) and (8):

$$E \approx -\frac{1}{2n} \ln 4\pi n.$$

Thus, (iii) is true.

(c) Let  $f(x) = \sqrt{\cos x}$ . For  $1 \leq i \leq n$ , the error in the sub-interval  $[\frac{\pi(i-1)}{3n}, \frac{\pi i}{3n}]$  is:

$$E_i = \frac{f''(\eta_i)}{24} \cdot \left(\frac{\pi}{3n}\right)^3, \quad \left(\eta_i \in \left(\frac{\pi(i-1)}{3n}, \frac{\pi i}{3n}\right)\right).$$

Hence the total error is:

$$E = \sum_{i=1}^n E_i = \sum_{i=1}^n \frac{f''(\eta_i)}{24} \left(\frac{\pi}{3n}\right)^3 = \frac{1}{24} \left(\frac{\pi}{3n}\right)^2 \sum_{i=1}^n f''(\eta_i) \cdot \frac{\pi}{3n}.$$

The sum on the right-hand side is a Riemann sum of the function  $f''$  on the interval  $[0, \frac{\pi}{3}]$ . Thus,

$$E \approx \frac{1}{24} \left(\frac{\pi}{3n}\right)^2 \int_0^{\pi/3} f''(x)dx = \frac{1}{24} \left(\frac{\pi}{3n}\right)^2 \left(f' \left(\frac{\pi}{3}\right) - f'(0)\right). \quad (9)$$

Now  $f'(x) = -\frac{\sin x}{2\sqrt{\cos x}}$ , so that (9) yields

$$E \approx \frac{1}{24} \left(\frac{\pi}{3n}\right)^2 \left(-\frac{\sin \pi/3}{2\sqrt{\cos \pi/3}} + \frac{\sin 0}{2\sqrt{\cos 0}}\right) = -\frac{\pi^2 \sqrt{6}}{864n^2}.$$

Thus, (i) is true.

4. (a) For the formula in question to be exact for all polynomials up to degree 2, it needs to hold for the polynomials  $1$ ,  $x$ ,  $x^2$ . Namely, the following equalities need to hold:

$$\begin{cases} w_1 \cdot 1 + w_2 \cdot 1 & = 1 \\ w_1 \cdot \frac{1}{3} + w_2 \cdot x_2 & = \frac{1}{2} \\ w_1 \cdot \frac{1}{9} + w_2 \cdot x_2^2 & = \frac{1}{3} \end{cases}$$

A routine calculation shows that the choice  $x_2 = 1$ ,  $w_1 = 3/4$  and  $w_2 = 1/4$  indeed yields a solution of the system.

Thus, (iv) is true.

- (b)  $P_1$  is not orthogonal to all constant polynomials. In fact

$$\begin{aligned} \langle P_1, 1 \rangle &= \int_0^1 P_1(x) dx \\ &= w_1 P_1(1/3) + w_2 P_1(x_2) \\ &= w_1 P_1(1/3) = 3/4 \cdot (1/3 - 1) \neq 0. \end{aligned}$$

The polynomial  $P_2$  is orthogonal to all constant polynomials. Indeed, for any constant  $c \in \mathbf{R}$

$$\langle P_2, c \rangle = \int_0^1 c P_2(x) dx = w_1 c P_2(1/3) + w_2 c P_2(x_2) = 0.$$

However,  $P_2$  is not orthogonal to all polynomials of degree not exceeding 1. For example,

$$\langle P_2, x - 1/3 \rangle = \int_0^1 (x - 1/3)^2 (x - 1) dx < 0,$$

since the only zeros of the integrand  $(x - 1/3)^2 (x - 1)$  are  $x = 1/3$  or  $x = 1$ , and for all other values of  $x \in [0, 1]$  it is negative.

Thus, (ii) is true.