Introduction to Computational and Biological Vision

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What does it mean to "recognize and object"?



- Retrieving information associated with an object that is not provided in the raw data (the image) itself
 - o Name
 - o **Type**
 - o **Class**
 - o **Function**
 - o What would it do to me if it caught me
 - •
 - •
- Matching against a knowledge base (memory)

Recognition as classification



- > Hierarchical
 - o My car
 - o Jeep
 - o Car
 - o Vehicle
 - o Man-made object
 - •

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 Classification level depends on application or circumstances.

How are objects recognized?

- Characteristic shape or structure
- Relative location
- Characteristic motion
- Color
- Texture
 - •
 - •
 - •

Issues in shape perception

•What is the "shape" of an object?

That spatial property of objects that don't change when certain spatial transformations are applied.

•Shape constancy

When does the same object have the same shape despite differences in viewing conditions

Shape equivalence

When do different objects (having different shapes) are seen as having the same shape

• How is shape equivalence determined?

What information and (algorithmic) operations are involved in determining shape equivalence?

Shape and object representation

Shape representation – viewer-centered templates



Shape representation – viewer-centered templates



Shape representation – viewer-centered feature vectors



Shape representation – viewer-centered feature vectors



Shape representation – object-centered components



Shape representation – object-centered components



Shape representation – object-centered components



Recognition vs. Localization

- **Recognition** What object from the database exists in the image?
 - Does this database object exist in the image?

Localization • What transformation would map the database object to the measured one.

Main approaches to recognition

- Appearance-based
- Feature alignment
- Parts and structural matching
- Shape invariances