

# Solution 1

## Question 1

- a) In the graph  $G$  there exists a cycle  $C = \{v, u\}$ . If we remove edge  $(v, u)$ , then remaining graph will consist of  $n$  vertices and  $n-1$  edges, a tree in other words. Lets remove edge  $(u, v)$  as well. We achieve an acyclic graph with  $n-2$  edges. Therefore, the graph contains exactly two connected components: one that includes  $u$ , and one that includes  $v$ .

Next, we need to prove that each component is a rooted tree, with roots  $u$  and  $v$ . (Separately for each component.)

This can be done by induction on the level: Let's start with the component of  $u$ :

Base: all the neighbors of  $u$  are oriented towards  $u$  since its out-degree is 0 in the component.

Step: Each vertex  $w$  in level  $i$  has a neighbor  $z$  in level  $i-1$ . Therefore, by the induction hypothesis  $z$  is oriented towards the root (i.e, towards a vertex in level  $i-2$ , that is different from  $w$ .) Since the out-degree of  $z$  is 1, the edge  $(z,w)$  cannot be oriented towards  $w$ . (Otherwise, the out-degree of  $z$  would be at least 2.) Therefore,  $(w, z)$  is oriented towards  $z$  in level  $i-1$ , or in other words, towards the root.

This completes the induction proof. The proof for the other component is similar.

- b) A path with  $n$  vertices and unique ascending edges.  
 $G = (V, E); V = \{v_1, v_2, \dots, v_n\}; E = \{(v_i, v_{i+1})\}; w(v_i, v_{i+1}) = i$   
Phase 0 -  $n$  fragments, each vertex is a fragment  
Phase 1 - a huge fragment made of all vertices from previous phase

- c) The runtime of GHS will be at least  $\log(n)$ , if fragment of each consecutive phase will include exactly two fragments from previous phase.

Such graph can be achieved, for example, as follows. Start with an unweighted  $n$ -vertex cycle  $\{v_1, v_2, \dots, v_n\}$ . Select an edge  $e_1 = (v_1, v_2)$ , and assign to it the weight 1. Next, skip the edge  $e_2 = (v_2, v_3)$ , and assign the edge  $e_3 = (v_3, v_4)$  the weight 2. Continue in this way until all the edges with odd index  $i$  are assigned the weight  $(i + 1)/2$ .

Next, go over the cycle again. Each other time you encounter an unweighted edge, assign it the last assigned value plus one. (After the second pass on the cycle, it has  $1/4n$  unweighted edges, where each two unweighted edges are separated by at least 3 weighted edges.) Next perform a third pass on the cycle with assigning the weights  $3/4n + 1, \dots, 7/8n$ , to each other unweighted edge. Continue with passes 4, 5, ...,  $\log n$ , in the same way, until all edges are assigned a weight

- d) The hypothesis is wrong. Lets build a clique with diameter 1, but GHS will have a runtime of  $\Omega(n)$ .

Assume a clique of  $n$  vertices with a lightweight path inside, just like in paragraph b, but this time the path consist of  $\frac{n}{2}$  vertices. In addition, assume that rest of the edges have very big weight.

In the first phase a huge fragment of  $\frac{n}{2}$  vertices will be created, it will include all the vertices of the lightweight path. The creation of the fragment will take  $\Omega(n)$  time. In addition, each CT for MWOE discovery will take  $\Omega(n)$  time as well.

## Question 2

We will use a variant of GHS, that (similarly to the standard GHS) works in  $O(\log n)$  phases:

- Since  $rt$  is connected to each vertex, we can use it as a super representative of all fragments. All messages to  $rt$  will include also an id of fragment.
- MWOE lookup will take  $O(1)$  time. Every fragment will send their edges to  $rt$  in  $O(1)$  time, that will calculate the MWOE for each fragment locally.
- Connecting of fragments is done in  $O(1)$  time also.
- Broadcasting the identity of the fragment's representative over each fragment is done in  $O(1)$  time. In standard GHS it may take up to  $O(\text{Diam}(F)) = O(n)$  time, but since  $rt$  is connected to each vertex, we can send direct messages to each vertex

$v \in F$  in  $O(1)$  time units.

Hence : Time (GHS') =  $O(\log n) * O(1) = O(\log n)$

Comm(GHS') =  $O(\log n) * O(E)$

### Question 3

- (a) Denote the identity mapping by  $Id$ . For any given rooted tree,  $(T, rt)$ , and any given set  $W$ , define  $Set_{T,W} := \{f \mid f \text{ is a bijection from } W \text{ to itself, such that } f^2 = Id\} - Id$ . For a bijection  $f$ , from  $W$  to  $W$ , define  $Sum_P(f) := \sum_{w \in W} P_w(f)$ . Let  $f_{min}$  satisfy:  $Sum_P(f_{min}) := \min\{Sum_f \mid f \in Set_{T,W}\}$ .

**Lemma 0.1.** For each pair of distinct vertices  $w, w' \in W$ , such that  $w' \neq f_{min}(w)$ , the paths  $P_w(f_{min})$  and  $P_{w'}(f_{min})$  are edge-disjoint.

*Proof.*

Assume for contradiction that there exist  $w_1, w_2 \in W$ , such that  $w_1 \neq f_{min}(w_2)$ , and there exists an edge  $e = (u, v)$ , such that

$|P_{w_1}(f_{min}) \cap P_{w_2}(f_{min})| \geq 1$ . It is easy to verify that  $P_{w_1}(f_{min}) \cup P_{w_2}(f_{min}) - P_{w_1}(f_{min}) \cap P_{w_2}(f_{min})$  is decomposed from the two following disjoint paths: Either from  $w_1$  to  $w_2$  and from  $f(w_1)$  to  $f(w_2)$ , or from  $w_1$  to  $f(w_2)$  and from  $w_2$  to  $f(w_1)$ . Without loss of generality the former decomposition is chosen. Define  $f'_{min}$  as follows:

$$f'_{min}(x) = \begin{cases} w_2, & x = w_1 \\ w_1, & x = w_2 \\ f_{min}(w_2), & x = f_{min}(w_1) \\ f_{min}(w_1), & x = f_{min}(w_2) \\ f_{min}(x), & \text{otherwise.} \end{cases}$$

Obviously,  $f'_{min} \in Set_{T,W}$ .  $Sum_P(f'_{min}) = Sum_P(f_{min}) - |P_{w_1}(f_{min}) \cap P_{w_2}(f_{min})| < Sum_P(f_{min}) := \min\{Sum_f \mid f \in Set_{T,W}\}$ , contradiction.

□

- (b) We will describe a distributed algorithm that finds such a bijection. The algorithm starts with the leaves, in a manner similar to *ConvergeCast*. Each leaf  $v \in W$  sends a *MATCH*( $v$ ) message, and each leaf  $v \in V \setminus W$  sends a *NOMATCH* message to its parent. Each vertex  $v \in V$  collects the *MATCH* and *NOMATCH* messages from its children, and keeps a set of vertices  $T$  which is the set of vertices that have sent a *MATCH* message. After all the children messages have arrived,  $v$  starts to match vertices. If  $|T|$  is even,  $v$  chooses random arbitrary pairs of vertices  $w_1, w_2 \in T$  and replies the messages *MATCHED*( $w_1, w_2$ ) to  $w_1$  and *MATCHED*( $w_2, w_1$ ) to  $w_2$ . Afterwards, if  $v \in W$ , it sends a *MATCH*( $v$ ) message to its parent. If  $|T|$  is odd,  $v$  chooses random arbitrary pairs of vertices  $w_1, w_2 \in T$  and sends the reply messages *MATCHED*( $w_1, w_2$ ) to  $w_1$  and *MATCHED*( $w_2, w_1$ ) to  $w_2$ . There will be one vertex  $w \in T$  that hasn't been paired, since  $|T|$  is odd. If  $v \in W$ , it will send a *MATCHED*( $w, v$ ) message to  $w$  and mark  $w$  as its paired vertex. Otherwise it'll send a *MATCH*( $w$ ) message to its parent and memoize the unmatched vertex  $w$ . When a node  $v \in V$  receives a *MATCHED*( $w_1, w_2$ ) message from its parent, it checks whether  $ID(v) = ID(w_1)$ . If so, it sets  $w_2$  as its match. Otherwise it sends the *MATCHED*( $w_1, w_2$ ) message to its unmatched child.

In the worst case, *MATCH* messages will go from a leaf to the tree root, and the *MATCHED* replies will go down back to the leaves. Since this communication is done concurrently,  $Time(FindMatch) = Depth(T) + Depth(T) = O(Depth(T))$ .

We can observe that each edge passes one *MATCH* or *NOMATCH* message and at most one *MATCHED* message, hence  $Comm(FindMatch) = O(|E|) = O(n)$ .