### The Assignment Problem

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### 1 Introduction

- Motivation
- Problem Definition

### 2 Algorithm

- Basic Idea
- Deficiency reduction
- Finding Maximum delta

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# Outline

#### 1 Introduction

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Motivation Problem Definition

Find the best way to assign each constructor with a job, paying the minimal cost.

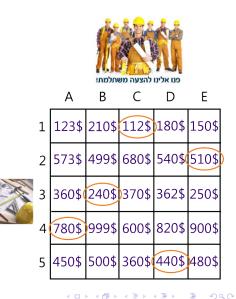
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2	573\$	499\$	680\$	540\$	510\$	
3	360\$	240\$	370\$	362\$	250\$	
4	780\$	999\$	600\$	820\$	900\$	
5	450\$	500\$	360\$	440\$	480\$	



Motivation Problem Definition

Find the best way to assign each constructor with a job, paying the minimal cost.

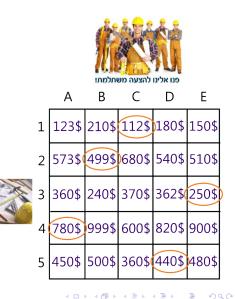
# Valid solution 2082\$



Motivation Problem Definition

Find the best way to assign each constructor with a job, paying the minimal cost.

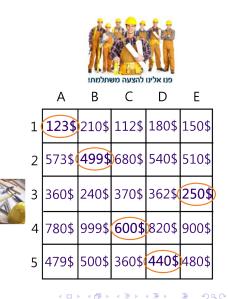
# Valid solution 2081\$



Motivation Problem Definition

Find the best way to assign each constructor with a job, paying the minimal cost.

### Optimal solution 1912\$



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Motivation Problem Definition

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### **Problem Definition**

#### Input:

Square matrix, A, of order n

#### Output:

A set of an *n* elements (cells), exactly one in each row and each column, such that the sum of these elements is minimal with respect to all such sets.

### So what is a solution?

A permutaion  $\beta$  over the set  $\{1, ..., n\}$ such that for any permutation  $\lambda$ :

$$\sum_{i=1}^{n} a_{i,\beta(i)} \leq \sum_{i=1}^{n} a_{i,\lambda(i)}.$$

In which cases is it easy to find the solution?

Example

4	6	2	2
З	1	3	1
5	3	4	3
2	5	2	5

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### Definition

Let some vector  $\Delta = (\Delta_1, ...., \Delta_n)$  be given. An element,  $a_{ij}$ , of the matrix A is called  $\Delta$ -minimal if

$$\forall_{1 \leq k \leq n} a_{ij} - \Delta_j \leq a_{ik} - \Delta_k$$

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Example:

	1	2	3	4
1	2	5	4	1
2	9	8	10	2
3	12	15	7	4
4	7	8	9	3
Δ	3	7	3	1



### Definition

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#### Example:

		1	2	3	4		1	2	3	
-	1	2	5	4	1	1	2		4	F
	2	9	8	10	2	$\frac{1}{2}$		_	•	
	3	12	15	7	4	$\rightarrow \frac{2}{3}$	12	15	7	
	4	7	8	9	3	4	_		9	
	Δ	3	7	3	1	·				



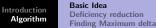
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$$\forall_{1 \leq k \leq n} \; a_{ij} - \Delta_j \leq a_{ik} - \Delta_k$$

#### Lemma

For any  $\Delta$  let there be given a set of  $n \Delta$ -minimal elements:  $a_{1j_1}, a_{2j_2}, \dots, a_{nj_n}$ , one from each row and each column. Then this set is an optimal solution for the Assignment Problem.

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#### Proof

- For some vector Δ = (Δ<sub>1</sub>, ...., Δ<sub>n</sub>).
   A set of n Δ-minimal elements has the minimal sum among all sets of n elements one from each column.
- **2** A set of  $n \Delta$ -minimal elements one from each row and each column is a minimal and valid solution.

For some vector  $\Delta = (\Delta_1, ..., \Delta_n)$ . A set of *n*  $\Delta$ -*minimal* elements has the minimal sum among all sets of n elements one from each column.

#### Proof:

Let there be a set of n elements  $a_{1j_1}, a_{2j_2}, ..., a_{nj_n}$ we can write the sum of the set as:

$$\sum_{i=1}^{n} a_{ij_i} = \sum_{k=1}^{n} \Delta_k + \sum_{i=1}^{n} (a_{ij_i} - \Delta_{j_i})$$

Let there be a set of  $n \Delta$ -minimal elements  $a^*_{1c_1}, a^*_{2c_2}, ..., a^*_{nc_n}$ 

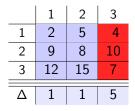
$$\sum_{i=1}^{n} a^*_{i_{c_i}} \leq \sum_{i=1}^{n} a_{i_{j_i}}$$

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### More definitions

- Given a vector Δ, an element a<sub>ij</sub> is a basic if it is a Δ-minimal element of the row i.
- A set of basics is a set of *n* basics, one from each row.
- *Deficiency* of a set of basics is the number of free columns, i.e. columns without a basic.



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# More definitions

- Given a vector  $\Delta$ , an element  $a_{ij}$  is a *basic* if it is a  $\Delta$ -*minimal* element of the row i.
- A set of basics is a set of *n* basics, one from each row.
- *Deficiency* of a set of basics is the number of free columns, i.e. columns without a basic.

	1	2	3		
1	2	5	4		
2	9	8	10		
3	12	15	7		
Δ 1 1 5					
deficiency=2.					

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Basic Idea Deficiency reduction Finding Maximum delta

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# Redfenition of problem

#### Input:

• Square matrix, A, of order n

#### Output:

- vector,  $\Delta$ , of size n
- a set of an *n* basics, with deficiancy 0.

# Integer linear programming problem

Given the n \* n matrix C we will define an n \* n matrix X of integer variables. The following constraints define the equivalent linear programming problem.

#### linear constraints:

• All the variables of X are 0 or 1:  
$$\forall i, j \ x_{i,j} \in \{0, 1\}.$$

2 In each row and column the sum of variables is 1:

$$\forall i \sum_{j=0}^{n} x_{i,j} = \sum_{j=0}^{n} x_{j,i} = 1.$$

#### Goal function:

minimize  $\sum_{i=0}^{n} \sum_{i=0}^{n} x_{i,j} c_{i,j}$ .

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# Primal-dual method

In the primal-dual method we generate a dual linear programing problem such that for every variable in the original problem we have a constraint in the dual problem, and for every constraint in the original we have a variable in the dual.

#### Basic Idea Deficiency reduction Finding Maximum delta

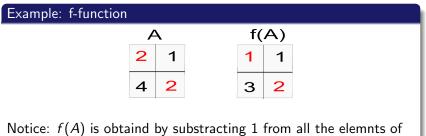
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### Primal-dual method

We iterate on the pairs: primal and dual solutions. At any time we have a NON-FEASIBLE primal solution S to the primal problem, while the dual solution PROVES that S is OPTIMAL among the "similarly non-feasible" primal solutions. In the end of the process we have a feasible, and thus optimal solution to the original problem.

### Intuition continues

We would want a function f such that for a matrix A with a soultion  $\beta$ , f(A) is a matrix for which  $\beta$  is a row minimal soultion.



Notice: f(A) is obtaind by substracting 1 from all the elemnts of the first column of A.

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### The function f

#### Input:

$$\Delta = (\Delta_1,....,\Delta_n)$$
, A an  $n*n$  matrix

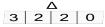
### Output: $f_{\Delta}(A) = B = (b_{i,j})$

for every indice  $(i,j) \in \{1,...,n\}^2$   $b_{i,j} = a_{i,j} - \Delta_j$ .

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7	8	4	2		
6	3	5	1		
8	5	6	3		
5	7	4	5		

f∆(A)					
4	6	2	2		
З	1	3	1		
5	3	4	3		
2	5	2	5		

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# Redfenition of problem

#### Input:

• Square matrix, A, of order n

#### Output:

- vector,  $\Delta$ , of size n
- a set of an *n* basics, with deficiancy 0.

### Deficiency reduction

We will solve this in an iterative maner, such that in each itration we will reduce the deficiency by 1.

#### Input:

- Square matrix, A, of order n
- vector,  $\Delta$ , of size n
- a set of *n* basics, with deficiancy m.

#### Output:

- vector,  $\Delta'$ , of size n
- a set of *n* basics, with deficiancy m-1.

In the first itration we start with  $\Delta = (0, ..., 0)$ , finding the basics and the deficiancy takes  $O(n^2)$ .

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# Phase 1 - Finding alternative Basics

We begin with vector  $\Delta$  and a set of basics  $a_{1,j(1)}, ..., a_{n,j(n)}$ 

7	8	4	2
6	3	5	1
8	5	6	3
5	7	4	5

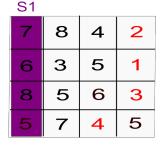


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### Phase 1 - Finding alternative Basics

Let  $s_1$  be the index of a free column.



# 0 0 0 0

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### Phase 1 - Finding alternative Basics

We will increase  $\Delta_{s_1}$  with maximal  $\delta_1$  such that all basics remain  $\Delta$ -minimal elements (lets assume we have a function which finds such a  $\delta$ ).

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7	8	4	2
6	3	5	1
8	5	6	3
5	7	4	5

δ=1

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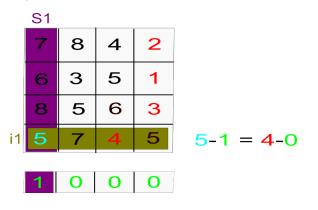
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### Phase 1 - Finding alternative Basics

We obtain that for some row index  $i_1 a_{i_1,s_1} - \Delta_{s_1} = a_{i_1,j(i_1)} - \Delta_{j(i_1)}$ .  $a_{i_1,s_1}$  is called an alternative basic.



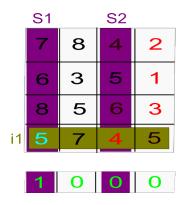
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Phase 1 - Finding alternative Basics

We define  $s_2 = j(i_1)$ .

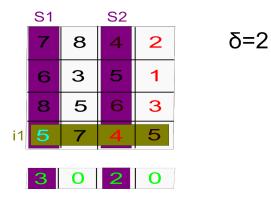


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# Phase 1 - Finding alternative Basics

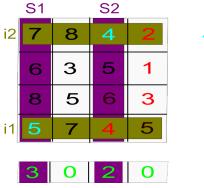
We now increase  $\Delta_{s_1}$ ,  $\Delta_{s_2}$  with maximal  $\delta_2$  such that all basics remain  $\Delta$ -minimal.



Basic Idea Deficiency reduction Finding Maximum delta

### Phase 1 - Finding alternative Basics

Again for same row index  $i_2 \neq i_1$   $a_{i_2,s_k} - \Delta_{s_k} = a_{i_2,j(i_2)} - \Delta_{j(i_2)}$ were  $k \in \{1, 2\}$ .  $a_{i_2,s_k}$  is an alternative basic.



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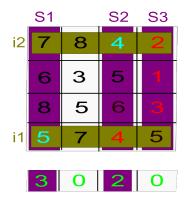
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### Phase 1 - Finding alternative Basics

We define  $s_3 = j(i_2)$ . We will continue this process until we find an alternative basic in a column with 2 or more basics.



### Phase 1 - Pseudo Code

Input:

- (a<sub>x,y</sub>) nxn matrix
- $\Delta$  *n* long vector
- j(i) function such that for each row  $a_{i,j(i)}$  is a basic

$$S = \{chooseEmptyColumn(j)\}$$
  
 $R = \{\}$ 

do:

$$\begin{split} \delta &= findMaxPreserving \Delta Minimalty(R, S, (a_{x,y}), \Delta, j(i)) \\ \text{for } s \in S \text{ do: } \Delta_s &= \Delta_s + \delta \\ \text{let } i \in \{1, ..., n\} \setminus R \text{ such that } \exists s \in S \ a_{i,j(i)} - \Delta_{j(i)} = a_{i,s} - \Delta_s. \\ R &= R \cup \{i\} \\ S &= S \cup \{j(i)\} \\ \text{while every column in } S \text{ has } 1 \text{ or } 0 \text{ basics.} \end{split}$$

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## Phase 1 - Complexity Analysis

In each step of phase 1:

- $\delta$  is found  $O(n^2)$
- $\Delta$  is updated O(n)

A new alternative basic is found (during the search of δ)- O(1)
 In each round the size of S incresses by 1, and S is bounded by n
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 There are at most n - 1 steps in phase 1.
 Total complexity: O(n)x[O(n<sup>2</sup>) + O(n) + O(1)] =
 O(n<sup>3</sup>)

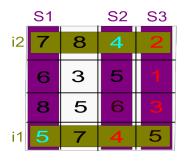
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# Phase 2 - Change of basics

Now as we mark a column  $(s_3)$  with 2 or more basics. This is the end of phase 1. We start changing our basics.



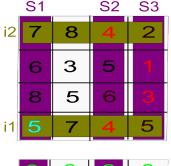


# Phase 2 - Change of basics

We reduce the number of basics for our last marked column by one.

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Basic Idea Deficiency reduction Finding Maximum delta

Image: A matrix

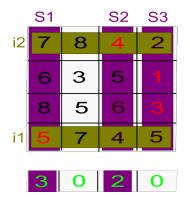
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# Phase 2 - Change of basics

In total we reduce the deficiency by 1.



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## Phase 2 - Complexity Analysis

#### The complexity of this step is O(n) as the number of basics.

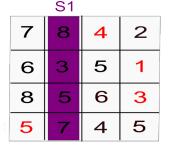
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### Example continues

We start phase 1 again and choose a column  $s_1$  with no basics.  $S = \{s_1\}$ .  $\Delta$  remains as it was built at the previous iteration  $\Rightarrow$  all basics remain  $\Delta$ -minimal.

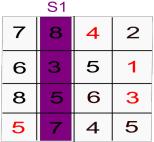




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### Example continues

We find a maximal  $\delta$  to add to  $\Delta_s$  were  $s \in S$ , such that it preserves  $\Delta$ -minimality.



ε δ=2

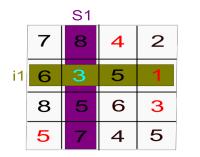
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### Example continues

For some row index  $i_1 a_{i_1,s_1} - \Delta_{s_1} = a_{i_1,j(i_1)} - \Delta_{j(i_1)}$ .  $a_{i_1,s_1}$  is an alternative basic.



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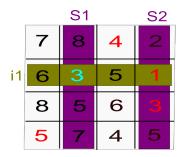
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## Example continues

We end phase 1 as we found a column  $j(i_1) = s_2 \in S$  with more then one basic.

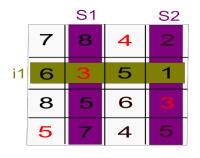




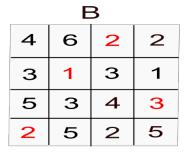
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### Example continues

Changing our basics leads us to a set of basics with deficiency m = 0. Therefor it is a optimal solution.  $B = (a_{i,j} - \Delta_j)$ .







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## Naive computation

$$\delta = \min_{i \in R, s \in S} [(a_{i,s} - \Delta_s) - (a_{i,j(i)} - \Delta_{j(i)})]$$

Where:

- R -set of row indices which **do not** contain alternative basics
- S -set of potential alternative basics column indices
- $(a_{x,y})$  -nxn matrix
- $\Delta$  -*n* long vector
- j(i) -function such that for each row  $a_{i,j(i)}$  is the basic in row i

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#### Computing $\delta$ in a strightforward manner takes $O(n^2)$

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# Total Complexity Analysis

- The maximum deficiency is n-1.
- In each itration we preform phase 1 + phase 2:  $O(n^3) + O(n)$

Total complexity:  $O(n)x[O(n^3) + O(n)] = O(n^4)$ 

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$$\delta = \min_{i \in R, s \in S} [(a_{is} - \Delta_s) - (a_{ij_i} - \Delta_{j_i})]$$

For each k, let b<sub>k</sub> = (b<sub>1k</sub>, ..., b<sub>nk</sub>) be a column of the values: b<sub>ik</sub> = [(a<sub>ik</sub> - Δ<sub>k</sub>) - (a<sub>iji</sub> - Δ<sub>ji</sub>)]
Let B be the nxn matrix: (b<sup>\*</sup><sub>1</sub>, ..., b<sup>\*</sup><sub>n</sub>), where b<sup>\*</sup><sub>k</sub> = Sort(b<sub>k</sub>)

Exa	ample	9		
	1	2	3	
1	2	5	4	
2	9	8	10	
3	12	15	7	
Δ	0	0	0	Ī

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Exa	ample	:					
	1	2	3			Ι.	1
1	2	5	4	$b_1$	<i>b</i> <sub>2</sub>	<i>b</i> <sub>3</sub>	
2	9	8	10	0	3	2	
3	12	15	7	1	0	2	
	-			5	8	0	
Δ	0	0	0				

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Algorithm	Finding Maximum delta

$$\delta = \min_{i \in R, s \in S} [(a_{is} - \Delta_s) - (a_{ij_i} - \Delta_{j_i})]$$

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Exa	ample	9											
	1	2	3					I	В				
1	2	5	4	-	$b_1$	<i>b</i> <sub>2</sub>	<i>b</i> <sub>3</sub>			$b_1^*$	$  b_2^*  $	b <sub>3</sub> *	
2	9	8	10		0	3	2		ľ	0	0	0	
3	12	15	7		1	0	2		Ī	1	3	2	
	0	0	0		5	8	0		Ī	5	8	2	
Δ	0	0	U										

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$$\delta = \min_{i \in R, s \in S} [(a_{is} - \Delta_s) - (a_{ij_i} - \Delta_{j_i})]$$

- For each k, let  $\frac{b_k}{b_k} = (b_{1k}, ..., b_{nk})$  be a column of the values:  $b_{i_k} = [(a_{i_k} - \Delta_k) - (a_{i_j} - \Delta_{j_i})]$
- Let B be the *nxn* matrix:  $(b_1^*, ..., b_n^*)$ , where  $b_k^* = Sort(b_k)$

What is the compexity of the construction of B?

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 $n \times O(n \log(n))$  $\downarrow$  $O(n^2 \log(n))$ 

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- As preprocessing phase of an iteration build matrix B O(n<sup>2</sup> log n).
- In each succeeding step of phase 1:
  - clear the matrix from items of rows which are not in R.  $n \times O(1) = O(n)$

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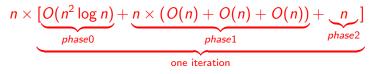


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$$\delta = \min_{i \in R, s \in S} [(a_{is} - \Delta_s) - (a_{ij_i} - \Delta_{j_i})] \downarrow$$

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$$\delta = \min_{i \in R} [\min_{s \in S} [(a_{is} - \Delta_s) - (a_{ij_i} - \Delta_{j_i})]]$$

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$$\delta = \min_{i \in R, s \in S} [(a_{is} - \Delta_s) - (a_{ij_i} - \Delta_{j_i})]$$

$$\downarrow$$

$$\delta = \min_{i \in R} [\min_{s \in S} [(a_{is} - \Delta_s)] - \underbrace{(a_{ij_i} - \Delta_{j_i})}_{\text{const. for a row}}]$$

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• At the begining of an iteration compute the column vector  $q_i$ In each succeeding step of phase 1:

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• update the vector q:

$$\forall i \ q_i \leftarrow \min[a_{is_m} - \Delta_{s_m}; q_i - \delta]$$

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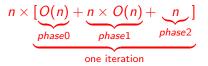
What is the total complexity?

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 $O(n)$ 

What is the total complexity?

 $O(n^3)$ 

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