

Scattering theory of Sturm-Liouville operator and a theory of vessels

FUNCTION THEORY AND OPERATOR THEORY: INFINITE DIMENSIONAL AND FREE SETTINGS,
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Classical Scattering theory on the half line.

Consider the following differential equation with the spectral parameter λ , defined on an interval \mathcal{I} , where $q(x)$ is called potential

$$-\frac{d^2}{dx^2}y(x) + q(x)y(x) = -i\lambda y(x), \quad -i\lambda = s^2 \quad (1)$$

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It was studied by C. Sturm [Stu36], R. Liouville [Lio95] in connection to dynamics, heat equation. Using monodromy preserving deformation problem of Linear Differential Equations (LDE) by L. Schlesinger [Sch08], R. Fuchs [Fuc07] and Garnier [Fuc12]. Using Riemann transformations by Marchenko [Mar] and using the scattering theory by Lax–Phillips [LxPh], Gelfand-Levitan [GL].



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Under condition $\int_0^\infty x|q(x)|dx < \infty$ [F] introduce Jost solutions

$$\phi(x, s) : \phi(0, s) = 0, \quad \phi'(0, s) = 1, \quad (2)$$

$$f(x, s) : \lim_{x \rightarrow \infty} e^{-isx} f(x, s) = 1. \quad (3)$$

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Define $M(s) = \phi'(x, s)f(x, s) - f'(x, s)\phi(x, s)$ and

$$\Omega(x, y) = 2/\pi \int_0^\infty \frac{\sin(kx)}{k} \left[\frac{1}{M(k)M(-k)} - 1 \right] \frac{\sin(ky)}{k} k^2 dk.$$

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Solve the Gelfand-Levitan equation [F, (8.5)]

$$K(x, y) + \Omega(x, y) + \int_0^x K(x, t)\Omega(t, y)dt = 0, \quad x > y. \quad (4)$$

from where $q(x) = 2 \frac{d}{dx} K(x, x)$.

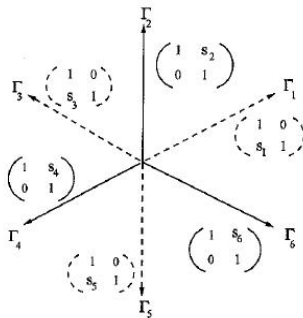


Airy equation.

For the solution of $u_{xx} = xu$, Consider the collection

$$\Gamma_k = \left\{ \lambda \mid \arg \lambda = \frac{2k-1}{6}\pi, \right\}$$

oriented towards infinity.



Let $\Gamma = \Gamma_2 \cup \Gamma_4 \cup \Gamma_6$. The classical solution of the Airy equation is

$$u(x) = \frac{i}{\pi} \left\{ s_2 \int_{\Gamma_2} + s_4 \int_{\Gamma_4} + s_6 \int_{\Gamma_6} \right\} e^{-\frac{8i}{3}\lambda^3 - 2ix\lambda} d\lambda,$$

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where $s_2 + s_4 + s_6 = 0$. On the other hand,

$u(x) = 2 \lim_{\lambda \rightarrow \infty} \lambda Y_{12}(\lambda)$, where $Y(\lambda, x)$ is the solution of the

abelian RH problem with contour Γ and $G(\lambda)$ given by

$$G(\lambda) = G(\lambda, x) = \begin{bmatrix} 1 & s_k e^{-\frac{8i}{3}\lambda^3 - 2ix\lambda} \\ 0 & 1 \end{bmatrix}, \quad \lambda \in \Gamma_k.$$

Second Painlevé equation

Augment the contour Γ by $\Gamma_1, \Gamma_3, \Gamma_5$ and jump matrix there:

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Add the following cyclic relations

$$s_{k+3} = -s_k, \quad k = 1, 2, 3; \quad s_1 - s_2 + s_3 + s_1 s_2 s_3 = 0. \quad (5)$$

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will satisfy nonlinear second-order differential equation

$$u_{xx} = xu + 2u^3. \quad (6)$$



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Proof of this fact is implicit: Bolibruch, Its, Kapaev [BIK].



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Correspondence is implemented through Gelfand-Levitan equation (1.) or Riemann Hilbert problem (2.,3.). Proof of (3.) involves completely integrable systems (Lax Pair).

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3. Vessels with prescribed singularities (on curves)

Overdetermined 2D systems and their transfer functions

2D systems, invariant in one direction (Phd thesis of A. M., V. Vinnikov, 2009 [M])

Overdetermined t_1 -invariant 2D system is a linear input-state-output (i/s/o) system of the form

$$\Sigma : \begin{cases} \frac{\partial}{\partial t_1} x(t_1, t_2) = A_1(t_2)x(t_1, t_2) + B(t_2)\sigma_1(t_2)u(t_1, t_2) \\ \frac{\partial}{\partial t_2} x(t_1, t_2) = A_2(t_2)x(t_1, t_2) + B(t_2)\sigma_2(t_2)u(t_1, t_2) \\ y(t_1, t_2) = u(t_1, t_2) - B^*(t_2)x(t_1, t_2) \end{cases} \quad (7)$$

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where for some Hilbert spaces \mathcal{H}, \mathcal{E}

$$\begin{aligned} A_1(t_2), A_2(t_2) &: \mathcal{H} \rightarrow \mathcal{H}, & B(t_2) &: \mathcal{E} \rightarrow \mathcal{H}, \\ \sigma_1(t_2), \sigma_2(t_2) &: \mathcal{E} \rightarrow \mathcal{E} \end{aligned}$$

are (bounded or not) operators. $u(t_1, t_2) \in \mathcal{E}$ and $y(t_1, t_2) \in \mathcal{E}$ are called the *input* and the *output*, $x(t_1, t_2) \in \mathcal{H}$ is called the *state*.



Demanding 1. complete integrability:

$$\frac{\partial}{\partial t_1} \left(\frac{\partial}{\partial t_2} x(t_1, t_2) \right) = \frac{\partial}{\partial t_2} \left(\frac{\partial}{\partial t_1} x(t_1, t_2) \right). \quad (8)$$

2. Mapping of the input $u(t_1, t_2)$

$$\sigma_2(t_2) \frac{\partial}{\partial t_1} u - \sigma_1(t_2) \frac{\partial}{\partial t_2} u + \gamma(t_2) u = 0. \quad (9)$$

to the output $y(t_1, t_2)$

$$\sigma_2(t_2) \frac{\partial}{\partial t_1} y - \sigma_1(t_2) \frac{\partial}{\partial t_2} y + \gamma_*(t_2) y = 0 \quad (10)$$

for some $\gamma(t_2), \gamma_*(t_2) : \mathcal{E} \rightarrow \mathcal{E}$.

3. Energy balances

$$\frac{\partial}{\partial t_1} \langle x, x \rangle + \langle \sigma_1 y, y \rangle = \langle \sigma_1 u, u \rangle,$$

$$\frac{\partial}{\partial t_2} \langle x, x \rangle + \langle \sigma_2 y, y \rangle = \langle \sigma_2 u, u \rangle$$

Overdetermined 2D systems and their transfer functions

t_1 -invariant vessel, A.M.-V. Vinnikov [MV1, MVc]

A t_1 -invariant conservative vessel as a collection of operators and spaces:

$$\mathfrak{V} = (A_1, A_2, B; \sigma_1, \sigma_2, \gamma, \gamma_*; \mathcal{H}, \mathcal{E})$$

which are all operator-functions of t_2 and satisfy certain regularity assumptions and the following axioms:

$$\frac{d}{dt_2} A_1 = A_2 A_1 - A_1 A_2,$$

$$A_1 + A_1^* + B \sigma_1 B^* = 0,$$

$$A_2 + A_2^* + B \sigma_2 B^* = 0,$$

$$\frac{d}{dt_2} (B \sigma_1) - A_2 B \sigma_1 + A_1 B \sigma_2 + B \gamma = 0,$$

$$\frac{d}{dt_2} (\sigma_1 B^*) + \sigma_1 B^* A_2 - \sigma_2 B^* A_1 - (\gamma_* + \frac{d}{dt_2} \sigma_1) B^* = 0,$$

$$\gamma = \sigma_2 B^* \tilde{B} \sigma_1 - \sigma_1 B^* \tilde{B} \sigma_2 + \gamma_*.$$

Remarks: 1. The first equation is the Lax equation, which plays an important role in completely integrable non-linear PDEs. It follows from the Lax equation that the spectrum of $A_1(t_2)$ is independent of t_2 . Defining the fundamental solution

$$\frac{d}{dt_2} F(t_2, t_2^0) = A_2(t_2) F(t_2, t_2^0), \quad F(t_2^0, t_2^0) = I,$$

we obtain

$$A_1(t_2) = F(t_2, t_2^0) A_1(t_2^0) F(t_2, t_2^0)^{-1}. \quad (11)$$

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- 2.** This object is interesting, because it is time varying on the one hand, but has all the advantages of the time-invariant case on the other hand: transfer function, functional model.
- 3.** We shall always assume that $\sigma_1(t_2)$ is invertible for all t_2 .

Overdetermined 2D systems and their transfer functions

Frequency domain analysis

Performing a partial separation of variables for the system (7),

$$u(t_1, t_2) = u_\lambda(t_2)e^{\lambda t_1},$$

$$x(t_1, t_2) = x_\lambda(t_2)e^{\lambda t_1},$$

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we arrive at the notion of the transfer function.



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Compatibility PDEs for $u(t_1, t_2)$, $y(t_1, t_2)$ become ODEs for $u_\lambda(t_2)$, $y_\lambda(t_2)$ with the spectral parameter λ ,

$$\lambda \sigma_2(t_2) u_\lambda(t_2) - \sigma_1(t_2) \frac{\partial}{\partial t_2} u_\lambda(t_2) + \gamma(t_2) u_\lambda(t_2) = 0,$$

$$\lambda \sigma_2(t_2) y_\lambda(t_2) - \sigma_1(t_2) \frac{\partial}{\partial t_2} y_\lambda(t_2) + \gamma_*(t_2) y_\lambda(t_2) = 0.$$



The corresponding i/s/o system becomes

$$\begin{cases} \lambda x_\lambda(t_2) = A_1(t_2)x_\lambda(t_2) + B(t_2)\sigma_1(t_2)u_\lambda(t_2) \\ \frac{d}{dt_2}x_\lambda(t_2) = A_2(t_2)x_\lambda(t_2) + B(t_2)\sigma_2(t_2)u_\lambda(t_2). \end{cases}$$

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The output $y_\lambda(t_2) = u_\lambda(t_2) - B^*(t_2)x_\lambda(t_2)$ may be found from the first i/s/o equation:

$$y_\lambda(t_2) = S(\lambda, t_2)u_\lambda(t_2),$$

using the **transfer function**

$$S(\lambda, t_2) = I - B^*(t_2)(\lambda I - A_1(t_2))^{-1}B(t_2)\sigma_1(t_2). \quad (12)$$

It turns out (A. M. 2011 [MSL]) that under certain conditions, one can obtain a simplified form. Defining

$\mathbb{X}^2(t_2) = F(t_2, t_2^0)F^*(t_2, t_2^0)$, and using transformation of the inner space, one can obtain that A_1 is constant and $A_2 = 0$. As a result there is obtained a simplified form of a vessel

$$\mathfrak{V} = (A, \mathbb{X}(t_2) = \mathbb{X}^*(t_2), B(t_2); \sigma_1, \sigma_2, \gamma, \gamma_*; \mathcal{H}, \mathcal{E})$$

where operators satisfy

$$0 = \frac{d}{dt_2}(B(t_2)\sigma_1(t_2)) + AB(t_2)\sigma_2(t_2) + B(t_2)\gamma(t_2), \quad (13)$$

$$A\mathbb{X}(t_2) + \mathbb{X}(t_2)A^* + B(t_2)\sigma_1(t_2)B^*(t_2) = 0, \quad (14)$$

$$\frac{d}{dt_2}\mathbb{X}(t_2) = B(t_2)\sigma_2(t_2)B^*(t_2), \quad (15)$$

$$\gamma_*(t_2) = \gamma(t_2) + \sigma_2(t_2)B^*(t_2)\mathbb{X}^{-1}(t_2)B(t_2)\sigma_1(t_2) \quad (16)$$

$$-\sigma_1(t_2)B^*(t_2)\mathbb{X}^{-1}(t_2)B(t_2)\sigma_2(t_2)$$

Review of a simplified vessel

Definition

A vessel in a simplified form is a collection:

$$\mathfrak{R}_{\mathfrak{M}} = (A, B(t_2), \mathbb{X}(t_2); \sigma_1, \sigma_2, \gamma, \gamma_*(t_2); \mathcal{H}, \mathcal{E}, I = [a, b]), \quad (17)$$

where $A, \mathbb{X}(t_2) = \mathbb{X}(t_2)^* : \mathcal{H} \rightarrow \mathcal{H}$, $B(t_2) : \mathcal{H} \rightarrow \mathcal{E}$ bounded, $\mathbb{X}(t_2)$ invertible on I

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where $A, \mathbb{X}(t_2) = \mathbb{X}(t_2)^* : \mathcal{H} \rightarrow \mathcal{H}$, $B(t_2) : \mathcal{H} \rightarrow \mathcal{E}$ bounded, $\mathbb{X}(t_2)$ invertible on I and

$$0 = \frac{d}{dx}(B(t_2)\sigma_1) + AB(t_2)\sigma_2 + B(t_2)\gamma, \quad (18)$$

$$A\mathbb{X}(t_2) + \mathbb{X}(t_2)A^* + B(t_2)\sigma_1 B(t_2)^* = 0, \quad (19)$$

$$\frac{d}{dx}\mathbb{X}(t_2) = B(t_2)\sigma_2 B(t_2)^*, \quad (20)$$

$$\gamma_*(t_2) = \gamma + \sigma_1 B(t_2)^* \mathbb{X}^{-1}(t_2) B(t_2) \sigma_2 - \sigma_2 B(t_2)^* \mathbb{X}^{-1}(t_2) B(t_2) \sigma_1 \quad (21)$$

Review of a simplified vessel (continued)

The vessel is associated to the completely integrable system

$$\Sigma : \begin{cases} \lambda x_\lambda(t_2) = A_1 x_\lambda(t_2) + B(t_2) \sigma_1(t_2) u_\lambda(t_2) \\ \frac{\partial}{\partial t_2} x_\lambda(t_2) = B(t_2) \sigma_2(t_2) u_\lambda(t_2) \\ y_\lambda(t_2) = u(t_1, t_2) - B^*(t_2) \mathbb{X}^{-1}(t_2) x_\lambda(t_2) \end{cases} \quad (22)$$

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And the transfer function

$$S(\lambda, t_2) = I - B^*(t_2)\mathbb{X}^{-1}(t_2)(\lambda I - A_1)^{-1}B(t_2)\sigma_1(t_2)$$

maps solutions $u_\lambda(t_2)$ to $y_\lambda(t_2)$ ($= S(\lambda, t_2)u_\lambda(t_2)$):

$$\begin{aligned} \lambda \sigma_2(t_2)u_\lambda(t_2) - \sigma_1(t_2)\frac{\partial}{\partial t_2}u_\lambda(t_2) + \gamma(t_2)u_\lambda(t_2) &= 0, \\ \lambda \sigma_2(t_2)y_\lambda(t_2) - \sigma_1(t_2)\frac{\partial}{\partial t_2}y_\lambda(t_2) + \gamma_*(t_2)y_\lambda(t_2) &= 0. \end{aligned}$$

Construction of a vessel

Starting from a function

$$S(\lambda, t_2^0) = I - B_0^* \mathbb{X}_0^{-1} (\lambda I - A)^{-1} B_0 \sigma_1,$$

for which $\mathbb{X}_0^* = \mathbb{X}_0$ and Lyapunov equation

$A\mathbb{X}_0 + \mathbb{X}_0 A^* + B_0 \sigma_1 B_0^* = 0$ holds, we solve first (18)

$$0 = \frac{d}{dx} (B(t_2) \sigma_1) + AB(t_2) \sigma_2 + B(t_2) \gamma, \quad B(x_0) = B_0.$$

Then we solve (20)

$$\frac{d}{dx} \mathbb{X}(t_2) = B(t_2) \sigma_2 B(t_2)^*, \quad \mathbb{X}(t_2) = \mathbb{X}_0$$

and define $\gamma_*(t_2)$ from γ using (21). Thus a vessel is created.

Sturm Liouville vessel parameters

Since variable t_1 disappeared in the equations, we use x from now on for t_2 .

Definition

Sturm Liouville parameters are

$$\sigma_1 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \sigma_2 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \gamma = \begin{bmatrix} 0 & 0 \\ 0 & i \end{bmatrix},$$

$$\gamma_*(x) = \begin{bmatrix} -i(\beta'(x) - \beta^2(x)) & -\beta(x) \\ \beta(x) & i \end{bmatrix}$$

for a real valued differentiable function $\beta(x)$, defined on an interval I .

Transfer function of a SL vessel

$$S(\lambda, x) = I - B(x) \mathbb{X}^{-1}(x) (\lambda I - A)^{-1} B(x) \sigma_1$$

Transfer function of a SL vessel

$$S(\lambda, x) = I - B(x) * \mathbb{X}^{-1}(x) (\lambda I - A)^{-1} B(x) \sigma_1$$

and multiplication by $S(\lambda, x)$ maps solutions $\begin{bmatrix} u_1(\lambda, x) \\ u_2(\lambda, x) \end{bmatrix}$ of

$$\begin{cases} -\frac{\partial^2}{\partial x^2} u_1(\lambda, x) = -i\lambda u_1(\lambda, x) \\ u_2(\lambda, x) = -i\frac{\partial}{\partial x} u_1(\lambda, x) \end{cases}$$

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to solutions $\begin{bmatrix} y_1(\lambda, x) \\ y_2(\lambda, x) \end{bmatrix} = S(\lambda, x) \begin{bmatrix} u_1(\lambda, x) \\ u_2(\lambda, x) \end{bmatrix}$ of

$$\begin{cases} -\frac{\partial^2}{\partial x^2} y_1(\lambda, x) + 2\beta'(x) y_1(\lambda, x) = -i\lambda y_1(\lambda, x) \\ y_2(\lambda, x) = -i\left[\frac{\partial}{\partial x} y_1(\lambda, x) - \beta(x) y_1(\lambda, x)\right]. \end{cases}$$

Construction of $S(\lambda, x_0)$ for a given potential

Fixing x_0 , for which the potential $q(x)$ is locally integrable in a small neighborhood,

Main Theorem

There exists a vessel on $x_0 \in I_0 \subseteq I$ realizing this potential (i.e. $2\beta'(x) = q(x)$).

Gelfand-Levitan equation for vessels

Defining

$$\Omega(x, y) = \begin{bmatrix} 1 & 0 \end{bmatrix} B(x)B^*(y) \begin{bmatrix} 1 \\ 0 \end{bmatrix},$$

$$K(x, y) = - \begin{bmatrix} 1 & 0 \end{bmatrix} B^*(x)\mathbb{X}^{-1}(x)B(y) \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

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one finds that Gelfand-Levitan (4) equation holds and

$$q(x) = 2\beta'(x) = 2\frac{d}{dx}K(x, x).$$

tau function

Definition

For a given realization

$$S(\lambda, x) = I - B^*(x)\mathbb{X}^{-1}(x)(\lambda I - A)^{-1}B(x)\sigma_1$$

tau function $\tau(x)$ is defined as

$$\tau = \det(\mathbb{X}^{-1}(x_0)\mathbb{X}(x)) \quad (23)$$

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Theorem

The following formula holds

$$q(x) = 2\beta'(x) = -2(\ln \tau(x))''$$



Let us choose a Jordan curve $\Gamma = -\Gamma^* = \{\mu(l) \mid l \in J\}$ and define

$$\mathcal{H} = L^2(\Gamma) = \left\{ f(\mu) \mid \int_J |f(\mu(l))|^2 dl < \infty \right\}.$$

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For a bounded interval it is a well defined operator. When Γ is unbounded, it is unbounded operator, with an obvious domain.

Define $B(x)$ as a solution of (18)

$$0 = \frac{d}{dx}(B(x)\sigma_1) + AB(x)\sigma_2 + B(x)\gamma,$$

Then it turns out that (without loss of generality)

$B(x) : \mathbb{C}^2 \rightarrow L^2(\Gamma)$ is an operator of multiplication on

$$B(\mu, x) = c(\mu) \left[\begin{array}{cc} \frac{\sin(tx)}{t} & -i \cos(tx) \end{array} \right], \mu = it^2.$$

Finally, we can define

$$\mathbb{X}(x)f(\mu) = \int_{\mathcal{J}} \frac{B(\mu, x)\sigma_1 B^*(\delta, x)}{i(\mu - \delta^*)} f(\delta) d\ell$$

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$$\mathbb{X}(x)f(\mu) = \int_{\mathcal{J}} \frac{B(\mu, x)\sigma_1 B^*(\delta, x)}{i(\mu - \delta^*)} f(\delta) d\ell$$

and $\gamma_*(x)$ by (21)

$$\gamma_*(x) = \gamma + \sigma_1 B(x)^* \mathbb{X}^{-1}(x) B(x) \sigma_2 - \sigma_2 B(x)^* \mathbb{X}^{-1}(x) B(x) \sigma_1$$

Lemma

The collection

$$\mathfrak{K}_b = (A, B(\mu, x), \mathbb{X}(x); \sigma_1, \sigma_2, \gamma, \gamma_*(x), L^2(\Gamma), \mathbb{C}^2, I),$$

is a vessel.



Choosing a vessel of this kind, one finds that

$$\begin{aligned} \int q(x) &= \text{Tr}(\mathbb{X}'(x)\mathbb{X}^{-1}) = \text{Tr}(B(x)\sigma_2 B^*(x)\mathbb{X}^{-1}) = \\ &= \begin{bmatrix} 1 & 0 \end{bmatrix} B^*(x)\mathbb{X}^{-1}B(x) \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \\ &= \int_J c^*(\mu) \frac{\sin(tx)}{t} \mathbb{X}^{-1} (c(\mu) \frac{\sin(tx)}{t}) d\ell \end{aligned}$$

Classical inverse scattering and its possible generalizations.

Construction of $S(\lambda, x_0)$ for a given $q(x)$ locally integrable potential on interval $[x_0, L]$ ($x_0 > 0$), uses inverse scattering theory for the potential

$$\tilde{q}(x) = \begin{cases} q(x), & x \in I, \\ 0, & x \notin I. \end{cases}$$

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In this case the obtained matrix $S(\lambda, x_0)$ and a corresponding vessel are defined on the curve $i\mathbb{R}_+$ (usually the whole curve). The generalization of the classical inverse scattering theory will be created, by studying the properties of the potential, obtained for other curves.



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Thank you